

Lezione 24

(M, ∇) varietà con connessione \dashrightarrow T torsione

Abbiamo visto tre tipi di funzioni bilineari $\mathcal{X}(M) \times \mathcal{X}(M) \rightarrow \mathcal{X}(M)$
su \mathbb{R}

- $[X, Y]$ \leftarrow $[X, Y]$ dipende da X e Y in $U(p)$
- $\nabla_x Y$ \leftarrow $\nabla_x Y$ dipende da $X(p)$ e da Y in $U(p)$
- $T^x(X, Y)$ \leftarrow $T(X, Y)(p)$ dipende solo da $X(p)$ e $Y(p)$

T è $\mathcal{C}^\infty(M)$ -lineare in entrambe le componenti:

$$T(fX, gY) = fgT(X, Y)$$

∇ è $\mathcal{C}^\infty(M)$ -lineare su X

$$\nabla_{fX} Y = f \nabla_X Y$$

Teo: (M, g) pR $\exists!$ ∇ simmetrica e compatibile

In carte

$$\Gamma_{ij}^k = g^{ke} \left(\frac{\partial g_{ie}}{\partial x^i} + \frac{\partial g_{ie}}{\partial x^j} - \frac{\partial g_{ij}}{\partial x^e} \right) \star$$

dim:

Usando compatibilit  e simmetria si vede che deve valere \star

  facile vedere che se definisco ∇ usando \star allora

∇ viene compatibile e simmetrica

$$\nabla g = 0$$

$$\Leftrightarrow \frac{\partial g}{\partial x} = g\Gamma + g\Gamma$$

Propriet  della connessione di Levi-Civita

Naturalit : Se $(M, g) \xrightarrow[\varphi]{} (N, h)$ isometria

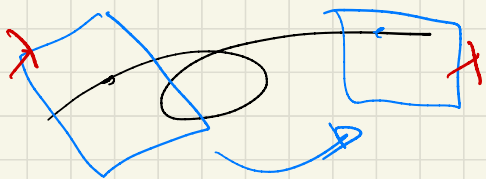
allora

$$\varphi_*: \nabla^g \longrightarrow \nabla^h$$

Riscalamento: $g \longmapsto \lambda g$ $\lambda \neq 0$ costante

$$\nabla^g = \nabla^{\lambda g}$$

resta compatibile



$\Gamma(X)_to$ è isom.

Esempi: \mathbb{R}^n

$\mathbb{R}^{p,q}$

$$g = \begin{pmatrix} -I_q \\ I_p \end{pmatrix}$$

$$\Gamma_{ij}^k = 0 \Rightarrow \nabla_v^g X = \frac{\partial X}{\partial v} + v^i X^j \Gamma_{ij}^k e_k = \frac{\partial X}{\partial v}$$

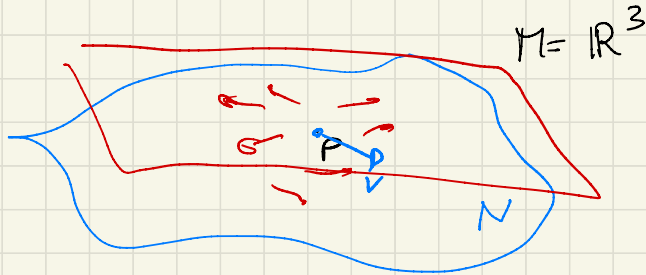
$\Rightarrow \nabla =$ derivata direzionale

Se $N \subseteq M$ sottovarietà pR di (M, g) pR

$$\nabla^M_{su M} \quad \nabla^N_{su N}$$

Prop: X campo in aperto di N

Lo estendo a M in modo arbitrario



Allora
 $\forall v \in T_p N$
 $\forall p \in N$

$$\nabla_v^N X = \pi \left(\nabla_v^M X \right)$$

\cong $T_p N$ \cong $T_p M$

$\pi: T_p M \rightarrow T_p N$ proiez. orb.

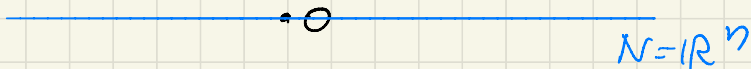
dim:

$$g|_{T_p M} \text{ non deg.} \Rightarrow T_p M = T_p N \oplus T_p N^\perp$$

In carte $M = \mathbb{R}^m$ $N = \mathbb{R}^n$

\mathbb{R}^m

$$p=0 \quad \mathbb{R}^n \subseteq \mathbb{R}^m$$



$$g(0) = \begin{pmatrix} g^1 & 0 \\ 0 & g^2 \end{pmatrix}$$

Se $1 \leq i, j, k \leq n$

$$\begin{aligned} \Gamma_{ij}^k & \text{ di } N \text{ in } p=0 \\ & = \Gamma_{ij}^k \text{ di } M \text{ in } p=0 \end{aligned}$$

$$\Gamma_{ij}^k = g^{ke} \left(\frac{\partial g_{ie}}{\partial x^i} + \frac{\partial g_{ie}}{\partial x^j} - \frac{\partial g_{ij}}{\partial x^e} \right)$$

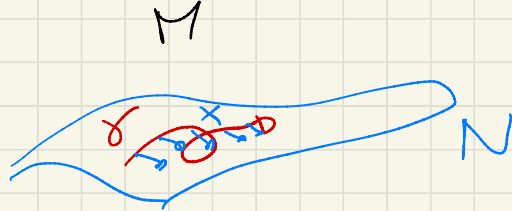
$$v \in T_p N \quad \nabla_v^N X = \frac{\partial X}{\partial v} + v^i X^j \Gamma_{ij}^k e_k$$

$$= \nabla_v^M X = \pi(\nabla_v^M X)$$

$$\nabla_v^M X = \frac{\partial X}{\partial v} + v^i X^j \Gamma_{ij}^k e_k$$

□

Cor:



$$D_t^N X = \pi \left(D_t^M X \right)$$

Cor:

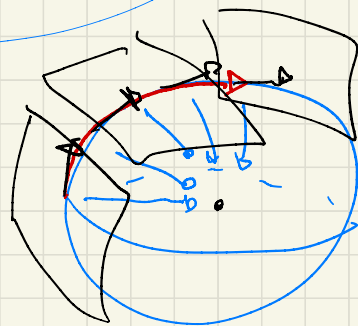
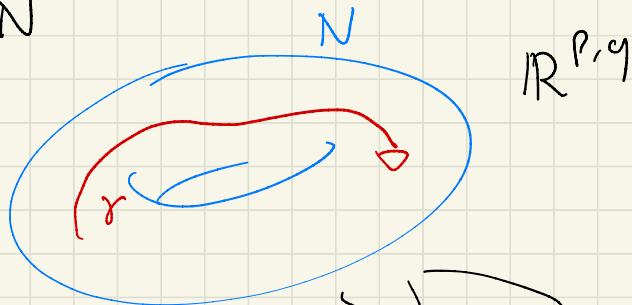
$$N \subseteq \mathbb{R}^{p,q}$$

$$\gamma: I \rightarrow N$$

$$X: I \rightarrow TN \quad \text{campo su } \gamma$$

$$\text{\u00e9 parallelo} \iff X'(t) \perp T_{\gamma(t)} N$$

derivata di X
in $\mathbb{R}^{p,q}$



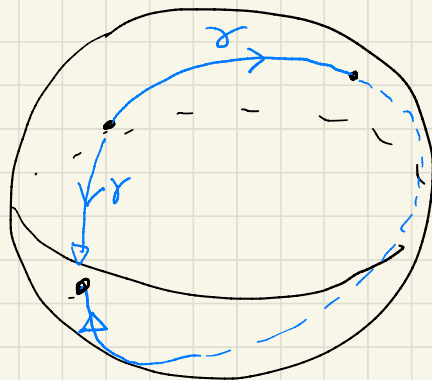
GEODETICHE

Def: (M, ∇)

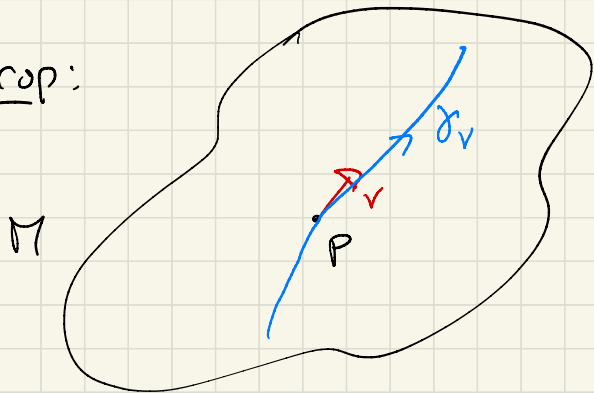
Una curva $\gamma: I \rightarrow M$ è **GEODETICA**

se $\gamma'(t)$ è parallelo.

Es: $\gamma: I \rightarrow M$ costante è geodetica
(cioè $\ddot{\gamma} = 0$)



Prop:



$(M, \nabla) \quad \forall p \in M, \forall v \in T_p M$
 $\exists! \gamma_v$ geodetica massimale
con $\gamma_v(0) = p, \gamma_v'(0) = v$
 $\gamma_v: I_v \rightarrow M \quad 0 \in I_v$

dim: in carte

$$\nabla_v X = \frac{\partial X}{\partial v} + v^i X^j \Gamma_{ij}^k e_k$$

$$\gamma \quad D_t X = \frac{dX}{dt} + \dot{\gamma}(t)^i X^j \Gamma_{ij}^k e_k \quad \gamma(t) = x(t)$$

$$\dot{\gamma}(t) = \dot{x}(t)$$

$$D_t X = \frac{dX}{dt} + \dot{x}^i X^j \Gamma_{ij}^k e_k \quad X = \dot{x}(t)$$

$$D_t \dot{x} = \ddot{x} + \dot{x}^i \dot{x}^j \Gamma_{ij}^k e_k = 0$$

$$\ddot{x} + \dot{x}^i \dot{x}^j \Gamma_{ij}^k e_k = 0$$

$$\ddot{x}_k + \dot{x}^i \dot{x}^j \Gamma_{ij}^k = 0 \quad \forall k$$

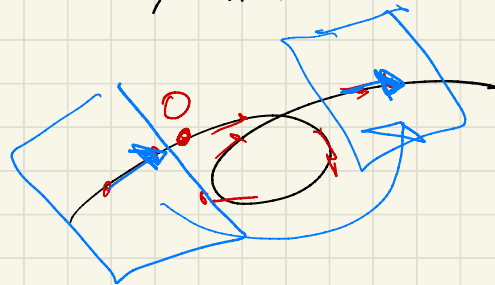
$$\ddot{x}_k = -\dot{x}^i \dot{x}^j \Gamma_{ij}^k$$

$\exists!$ soluzione con dati iniziali: $x(0) = p \quad \dot{x}(0) = v$

Oss: Se γ geod è non banale, allora è immersione ($\dot{\gamma}(t) \neq 0$ $\forall t$)

dim: Se $\dot{\gamma}(t) = 0$
per un $t \in I$ allora

$\dot{\gamma}(t) = 0 \quad \forall t \in I$.



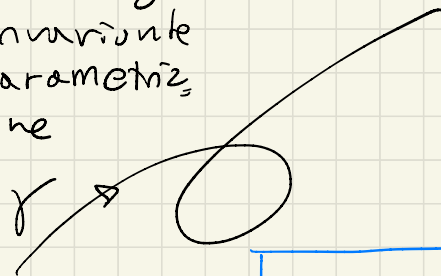
Oss: $\|\dot{\gamma}(t)\|$ è cost.

Oss: Essere geod.
non è invariante
per riparametriz-
zazione

Prop: Se γ è geodetica, allora

$\forall c \neq 0 \quad \eta(t) = \gamma(ct + d)$

$\forall d \in \mathbb{R} \quad \eta$ è geodetica



dim: X campo parallelo su $\gamma \rightarrow cX$ è parallelo
NON BASTA IN REALTÀ

$\dot{\gamma}_v(ct) = \dot{\gamma}_{cv}(t)$

p.l.a.

$\|\dot{\gamma}\| = 1$

si può fare $\|\dot{\gamma}\| \neq 0$

$$c^2 \nabla_v X = \nabla_{cv} cX$$

$$\nabla_v X = 0 \Rightarrow \nabla_{cv} cX = 0$$

Esempi: $\mathbb{R}^{p,q}$

$$\Gamma_{ij}^k = 0$$

$$\ddot{x}^k = 0 \quad \forall k$$

Le geodetiche sono

$$x(t) = p + tv$$

Sono definite su \mathbb{R}

$N \subseteq \mathbb{R}^{p,q}$ sottovarietà pR

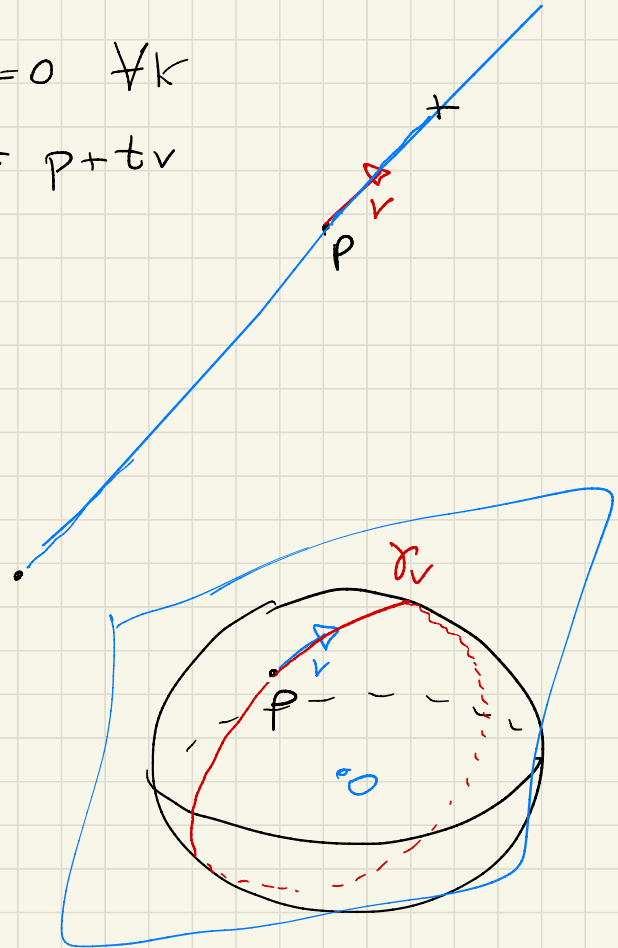
$$\nabla_v = \frac{\partial}{\partial v}$$

$x: I \rightarrow N$ geodetica

$$\Leftrightarrow \ddot{x}(t) \perp T_{x(t)} N$$

SFERA: $S^n \subseteq \mathbb{R}^{n+1}$ v unitario

$$\gamma_v(t) = \cos t \cdot p + \sin t \cdot v$$



1) \bar{e} geod: $\ddot{\gamma}_v(t) \perp T_{\gamma(t)} = \gamma(t)^\perp$

infatti $\ddot{\gamma}_v(t) = -\gamma_v(t)$

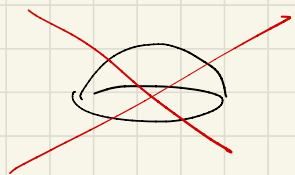
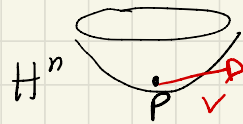
2) $\gamma_v(0) = p$ $\dot{\gamma}_v(0) = v$

0) $\gamma_v(t) \in S^n$

SPAZIO IPERBOLICO

$\|v\|=1$ $H^n \subseteq \mathbb{R}^{n,1}$

$\begin{pmatrix} -1 \\ + \\ + \\ \vdots \\ + \\ +1 \end{pmatrix}$



$\gamma_v(t) = \cosh t \cdot p + \sinh t \cdot v$

$\cosh t = \frac{e^t + e^{-t}}{2}$

$\sinh t = \frac{e^t - e^{-t}}{2}$

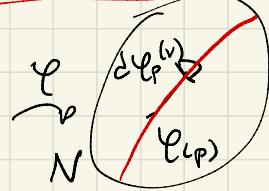
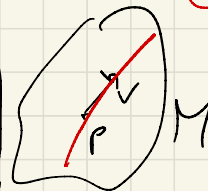
Una geodetica è di tipo
TEMPO, SPAZIO o LUCE
a seconda di $\gamma'(t)$.
(non dip. da t)

Se $\varphi: (M, g) \xrightarrow{\sim} (N, h)$
isometria

manda geodetiche
in geodetiche

γ in M is $\varphi \circ \gamma$ geod. in N

$\varphi \circ \gamma_v = \gamma_{d\varphi(v)}$



$$\cosh^2 t - \sinh^2 t = 1$$

$$d \sinh = \cosh$$

$$d \cosh = \sinh$$

1) \bar{e} geod.

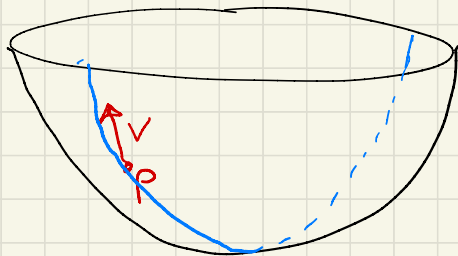
$$\ddot{\gamma}_v^{(t)} = \gamma_v^{(t)}$$

$$T_{\gamma_v^{(t)}} H^n = \gamma_v^\perp$$

2) $\gamma_v(0) = p$

$\gamma_v(1) = v$

or



0) $\gamma_v(t) \in H^n$

(es)

Span(p, v)